

# Maggie A. Collier

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Webpage : <https://collierma.github.io>

PH.D. STUDENT IN ROBOTICS, ROBOTICS INSTITUTE, CMU

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**EDUCATION**      **Carnegie Mellon University (CMU)**, Pittsburgh, Pennsylvania      *2019 - present*  
Ph.D. in Robotics, Robotics Institute  
Advisor: Prof. Henny Admoni, [Human and Robots Partners \(HARP\) Lab](#)  
Areas of Study: Human Robot Interaction, Assistive Robotics, Assistive Teleoperation

**University of Alabama at Birmingham (UAB)**, Birmingham, Alabama      *2013 - 2019*  
B.S. in Electrical Engineering (EE), *Summa Cum Laude*  
B.S. in Biomedical Engineering (BME), *Summa Cum Laude*  
Thesis: Eye Gaze Behavior during Teleoperation of a Robot in a Multi-stage Task  
GPA: 3.98/4.0

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**SUMMARY**      I am a researcher with multidisciplinary experience in *robotics, biomedical device development, and tissue engineering*. My current research interests include *Human Robot Interaction, Assistive Robotics, and Healthcare Robotics*.

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**RESEARCH EXPERIENCE**      **Users' Preferences for Assistance throughout Human-Robot Collaboration Tasks**  
*Human and Robot Partners Lab, CMU*      *Feb '21 - present*  
Advisor: Prof. Henny Admoni  
Aim: Study users' preference for assistance during teleoperated object manipulation tasks

- Wrote code to enable people to directly adjust the way their input commands and the robot's commands are arbitrated in an assistive teleoperation paradigm
- Designing and building a user study to test how people's preferences for assistance change throughout an object manipulation task

**Eye Gaze Behavior during Teleoperation of a Robot in a Multi-stage Task**  
*Human and Robot Partners Lab, CMU*      *June '18 - Dec '20*  
Advisor: Prof. Henny Admoni  
Aim: Study eye gaze behavior during complex, teleoperated object manipulation tasks

- Designed and conducted a user study to collect eye gaze during complex robot manipulation
- Studied eye gaze behavior while users teleoperate a robot to perform a multi-stage task
- Studied approaches for distinguishing subtasks during a teleoperated multi-stage task with gaze

**Human Pose Tracking with Capacitive Proximity Sensor in Robot Assisted Dressing**  
*Healthcare Robotics Lab, Georgia Institute of Technology*      *May '17 - Aug '17*  
Advisor: Prof. Charlie Kemp  
Aim: Equip a robot to manage errors in human pose estimation and adapt to human motion in real time during robot assisted dressing

- Built a sensor that can estimate the distance between a robot's end effector and a person
- Aided in implementing a PD controller on a PR2 robot
- Helped design a human study to evaluate a novel approach to error management during robot assisted dressing

**Improving Coil Embolization of Brain Aneurysms**  
*Department of Biomedical Engineering, UAB*      *Oct '14 - May '17*  
Advisors: Prof. Ho-Wook Jun; Patrick Hwang, Ph.D.

Aim: Increase occlusion rates of brain aneurysms treated with coil embolization in an effort to phase out a more invasive treatment

- Assisted in the project's creation by providing ideas for strategies to increase occlusion rates
- Independently designed and conducted the *in vitro* experiments
- Built a statistical analysis program in MATLAB to process data from the *in vitro* studies
- Prepared and sent samples to collaborators at the Mayo Clinic for the *in vivo* studies

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PUBLICATIONS    Z. Erickson, M. Collier, A. Kapusta, C. C. Kemp (2018). "Tracking Human Pose During Robot-Assisted Dressing using Single-Axis Capacitive Proximity Sensing" in *IEEE Robotics and Automation Letters (RA-L)*

M. Collier, R. Aronson, H. Admoni (2018). "Eye Gaze Behavior during Teleoperation of a Robot in a Multi-stage Task" in *Robotics Institute Summer Scholars (RISS) Working Papers Journal*

CONFERENCE PRESENTATIONS    M. Collier, H. Admoni (Oct '23). "Uncovering People's Preferences for Robot Autonomy in Assistive Teleoperation" presented at the *Assistive Robotics for Citizens Workshop at IROS 2023*

T. J. Hwang, M. Collier, G. Alexander, B. Brott, R. Hergenrother, R. Kardivel, D. Kallmes, H.-W. Jun (Oct '17). "Nitric Oxide Releasing Bionanomatrix Coating for Brain Aneurysm Coils to Improve Healing" presented at the *2017 Biomedical Engineering Society Annual Meeting*

M. Collier, M. Chan, D. Chasteen-Boyd, S. Holder, A. Eberhardt (Apr '17). "An Independent Alarm Clock Designed for Individuals with Deaf-Blindness" presented in the *2017 Design of Medical Devices Conference* at the University of Minnesota

M. Collier (Apr '17). "Novel Endothelium-Mimicking Nanomatrix Coating to Enhance Healing of Ruptured Intracranial Aneurysms Treated with Coil Embolization" presented at the *2017 National Conference on Undergraduate Research (NCUR)* at the University of Memphis

T. J. Hwang, M. Collier, G. Alexander, B. Brott, R. Hergenrother, R. Kardivel, D. Kallmes, H.-W. Jun (Oct '16). "A Self-assembled Bionanomatrix Coating for Intracranial Aneurysm Coils to Enhance Healing" presented at the *2016 Biomedical Engineering Society Annual Meeting*

T. J. Hwang, G. Alexander, M. Somarathna, M. Collier, B. Brott, J. Pollock, T. Lee, H.-W. Jun (Oct '16). "Nitric Oxide Releasing Nanomatrix to Enhance Dialysis Fistula Maturation" presented at the *2016 Biomedical Engineering Society Annual Meeting*

M. Collier, T. J. Hwang, B. Brott, R. Hergenrother, R. Kardivel, D. Kallmes, and H.-W. Jun (May '16). "Novel Endothelium-Mimicking Nanomatrix Coating to Enhance Healing of Ruptured Intracranial Aneurysms Treated with Coil Embolization" presented at the *9th Frontiers in Chemistry and Biology Interface Symposium* at Johns Hopkins University

M. Collier, T. J. Hwang, G. Alexander, B. Brott, R. Hergenrother, R. Kardivel, D. Kallmes, H.-W. Jun (Apr '16). "Improving Coil Embolization of Intracranial Aneurysms through the Application of a Nitric Oxide-Releasing Nanomatrix Coating" presented at the *2016 University of Alabama System Honors Research Conference* at the University of Alabama at Huntsville

G. Alexander, J. Vines, M. Collier, T. J. Hwang, J. Kim, B. Brott, H.-W. Jun (Oct '15). "Evaluation of Inflammation on a Self-Assembled Nanomatrix Stent Coating *In Vitro*" presented at the *2015 Biomedical Engineering Society Annual Meeting*

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HONORS & AWARDS	National Defense Science and Engineering Graduate Fellowship	2019
	National Science Foundation Graduate Research Fellowship ( <i>declined</i> )	2019
	Goldwater Scholarship	2017
	Outstanding Student Engineer in Biomedical Engineering at UAB	2017

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SKILLS	<b>Programming:</b> Python ( <i>proficient</i> ), MATLAB ( <i>experienced</i> ), C++/C ( <i>familiar</i> ) <b>Software:</b> ROS, MoveIt, Git, SolidWorks, LabVIEW	
TEACHING EXPERIENCE	<b>Teaching Assistantships</b> <ul style="list-style-type: none"> <li>Math Fundamentals for Robotics (CMU, 16-811) – Prof. Mike Erdmann <i>Fall 2023</i></li> <li>Human Robot Interaction (CMU, 16-467) – Prof. Henny Admoni <i>Spring 2021</i></li> <li>Signals and Systems (UAB, EE 318) – Dr. Arie Nakhmani <i>Fall 2018</i></li> <li>Bioimaging (UAB, BME 340) – Dr. Massimo Fazio <i>Spring 2017</i></li> <li>Bioinstrumentation (UAB, BME 313) – Dr. Joel Berry <i>Fall 2016</i></li> </ul>	
	<b>Supplemental Instruction</b> <i>Jan '17 - Apr '19</i> Employer: Vulcan Materials Academic Success Center, UAB Served as Supplemental Instruction leader to Introductory Physics course for four semesters <ul style="list-style-type: none"> <li>Taught large groups of pre-medicine students about physics</li> <li>Created and worked practice problems for students at two one-hour, weekly sessions</li> <li>Created and hosted mock tests for students prior to class tests</li> <li>Collaborated with professors to develop useful content for sessions</li> </ul>	
	<b>Tutoring</b> <i>Jan '15 - Dec '16</i> Employer: Vulcan Materials Academic Success Center, UAB <ul style="list-style-type: none"> <li>Tutored approximately 10 hours a week in challenging courses such as Calculus, Physics, Biology, and Organic Chemistry</li> <li>Certified with the Association of Tutoring Professionals</li> </ul>	
SERVICE	<b>Reviewer:</b> ACM/IEEE International Conference on Human Robot Interaction <i>Fall 2023</i> <b>Reviewer:</b> Int. Conference on Robotics and Automation, Robotics and Automation Letters <i>Fall 2021</i> <b>Reviewer:</b> Int. Conference on Intelligent Robots and Systems <i>Spring 2020</i> <b>Reviewer:</b> Robotics Institute Summer Scholars Admissions Committee <i>Spring 2020, Spring 2021</i> <b>Mentor:</b> Robotics Institute Summer Scholars Program <i>Summer 2020</i>	
ADDITIONAL EXPERIENCE	<b>Autonomous Robot for Hardware Competition</b> <i>Aug '18 - Apr '19</i> EE Senior Capstone Project, Department of Electrical Engineering, UAB Aim: Build an autonomous robot for IEEE Southeast Conference student competition <ul style="list-style-type: none"> <li>Implemented the localization component of the project with a Lidar and a variant of ICP</li> <li>Setup the Raspberry Pi with light-weight versions of Linux and ROS</li> <li>Gained more experience with real-time processing and embedded systems</li> </ul>	
	<b>Alarm Clock for People with Deaf-Blindness</b> <i>Sept '16 - Apr '17</i> BME Senior Capstone Project, Department of Biomedical Engineering, UAB Aim: Develop an alarm clock for individuals with deaf-blindness that can be set without assistance from a caretaker <ul style="list-style-type: none"> <li>Implemented a novel time and alarm setting input mechanism to meet users' needs</li> <li>Designed the entire electrical circuit and programmed the Arduino</li> <li>Helped secure a provisional patent for novel input mechanism</li> </ul>	
	<b>Journal Editorship</b> <i>Sept '14 - May '17</i> <a href="#">Inquiro</a> , UAB's official peer-reviewed undergraduate research journal	

- Oversaw the publication of Volume IX and X
- Served on editorial board for Volume VIII
- Argued for and secured funding for a website rebuild from the Office of the Provost to make *Inquiرو* a visually appealing, open-access online publication